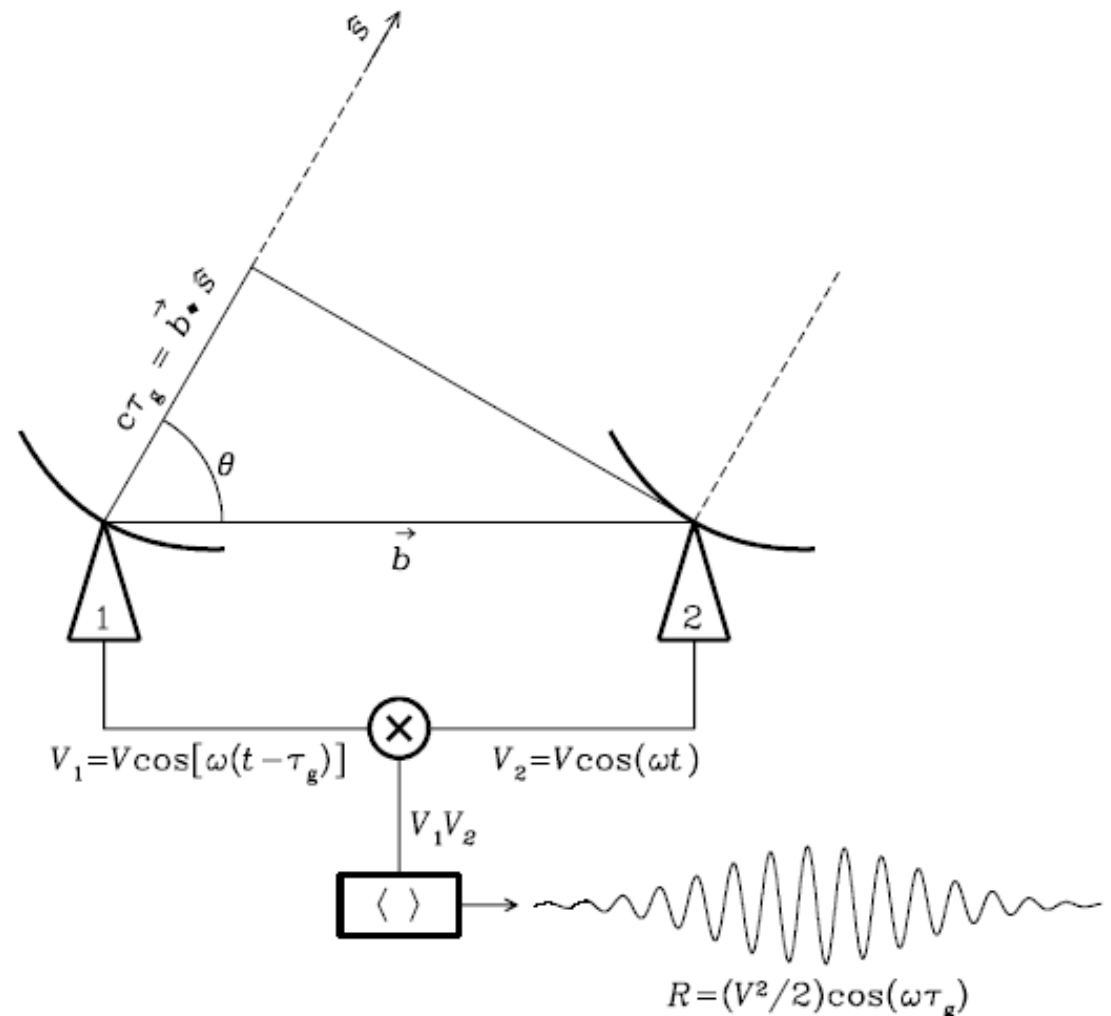


Radio Interferometry

- Two-element interferometry
- Visibilities
- Aperture synthesis
- Imaging considerations

Two-element Interferometer

- Correlate and integrate the signals from two antenna separated by baseline, b , pointing at the same source
- Produces an interference fringe



- The term modulating the fringes $\cos(\omega\tau_g)$ can be rewritten using

$$\omega = 2\pi\nu \quad \text{and} \quad \tau_g = \frac{b \cos \theta}{c} = \frac{\vec{b} \cdot \hat{s}}{c}$$

to become

$$\cos\left(2\pi\nu \frac{\vec{b} \cdot \hat{s}}{c}\right) = \cos\left(2\pi \frac{\vec{b}}{\lambda} \cdot \hat{s}\right) = \cos(2\pi \vec{b}_\lambda \cdot \hat{s})$$

where $\vec{b}_\lambda$ is the baseline measured in wavelengths representing a *spatial frequency*

Complex Visibility

- For an extended source we must integrate over solid angle and the response of the interferometer can then be written as

$$V_{\nu} = \int I_{\nu}(\hat{s}) e^{(-i 2 \pi \vec{b}_{\lambda} \cdot \hat{s})} d\Omega$$

where this *visibility* is a complex number that can be expressed in terms of *amplitude* and *phase*

$$V = A e^{-i\phi}$$

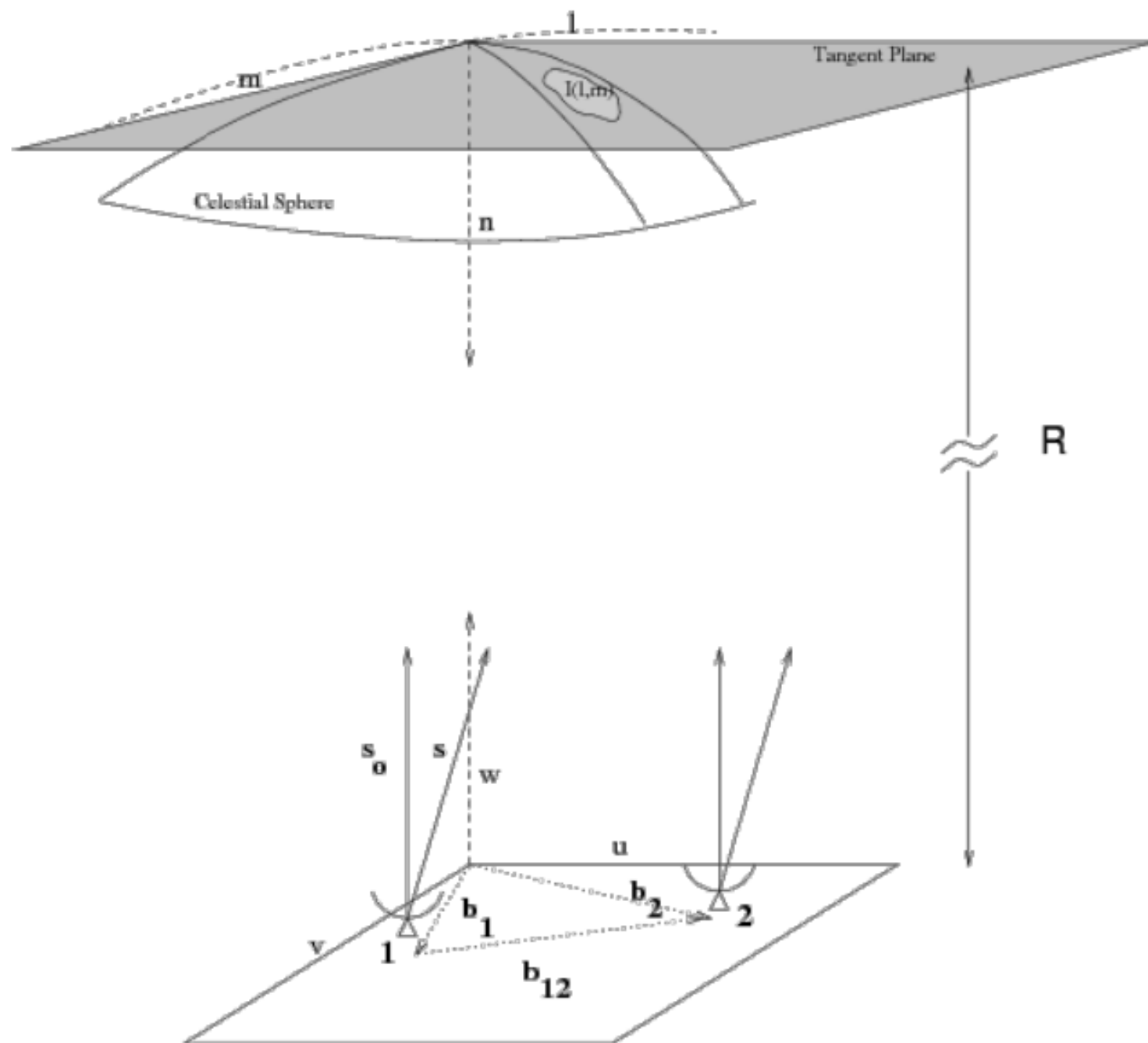
uv plane

- In 2D we can define a plane perpendicular to the source direction in which to define the baseline vector in terms of spatial frequency coordinates u and v , i.e.

$$\vec{b}_\lambda = u + v$$

- And the source position unit vector is defined by direction cosines projected on the uv plane

$$\hat{s} = l + m$$



- The visibility now becomes

$$V_v(u, v) = \int I_v(l, m) e^{(-i 2 \pi (ul + vm))} dl dm$$

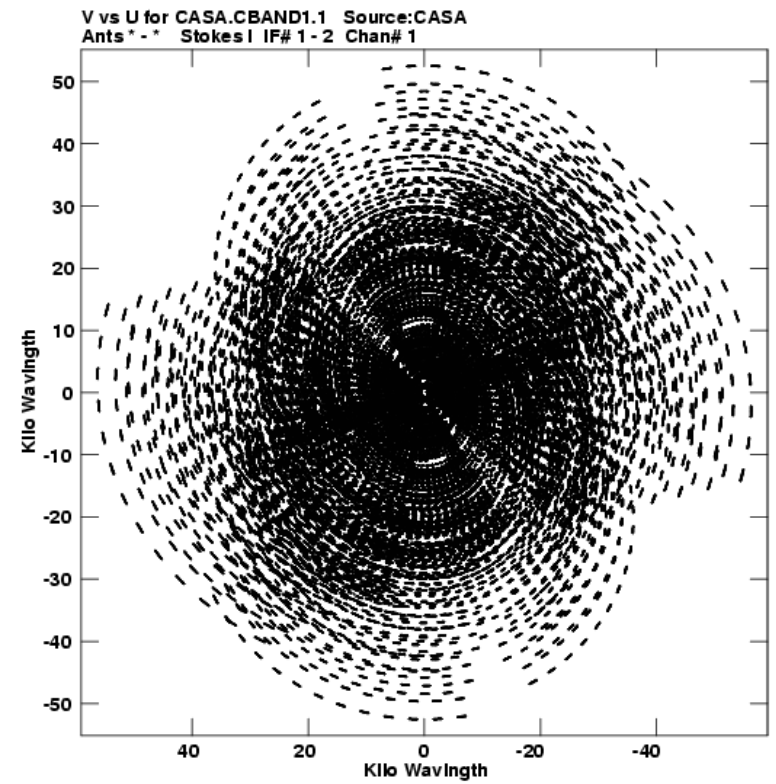
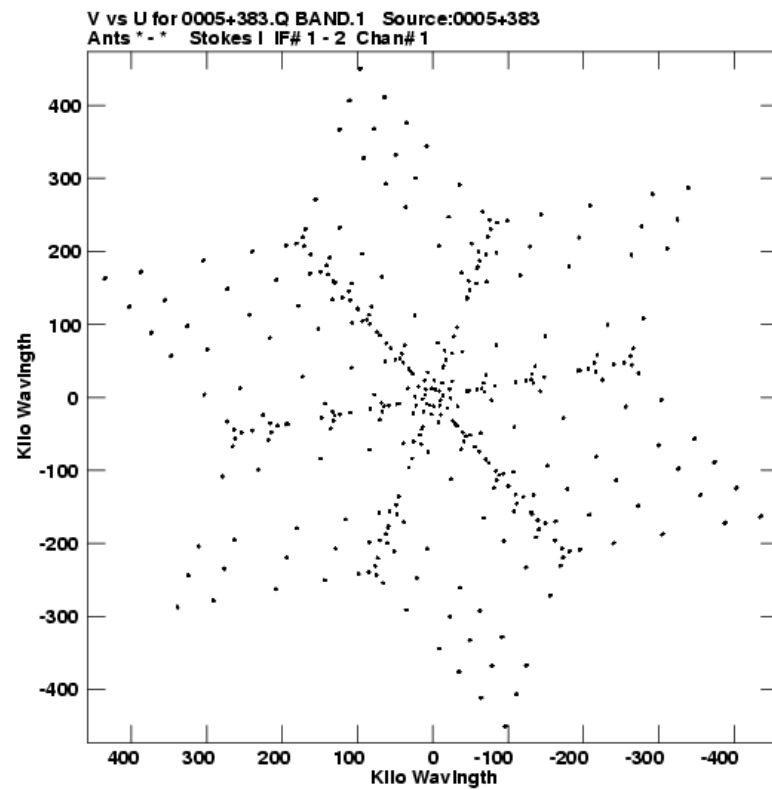
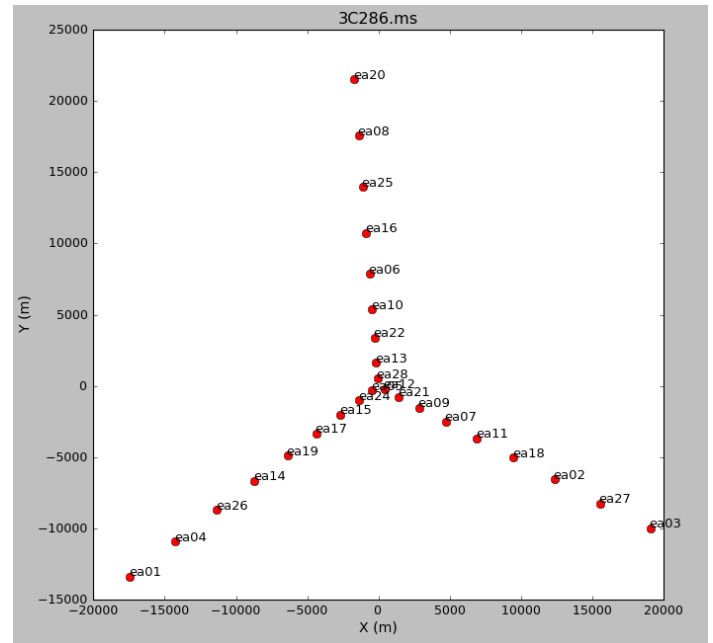
which is the Fourier transform of the intensity distribution

- Hence the intensity distribution can be recovered from the inverse Fourier transform of the visibilities

$$I_v(l, m) = \int V_v(u, v) e^{(i 2 \pi (ul + vm))} du dv$$

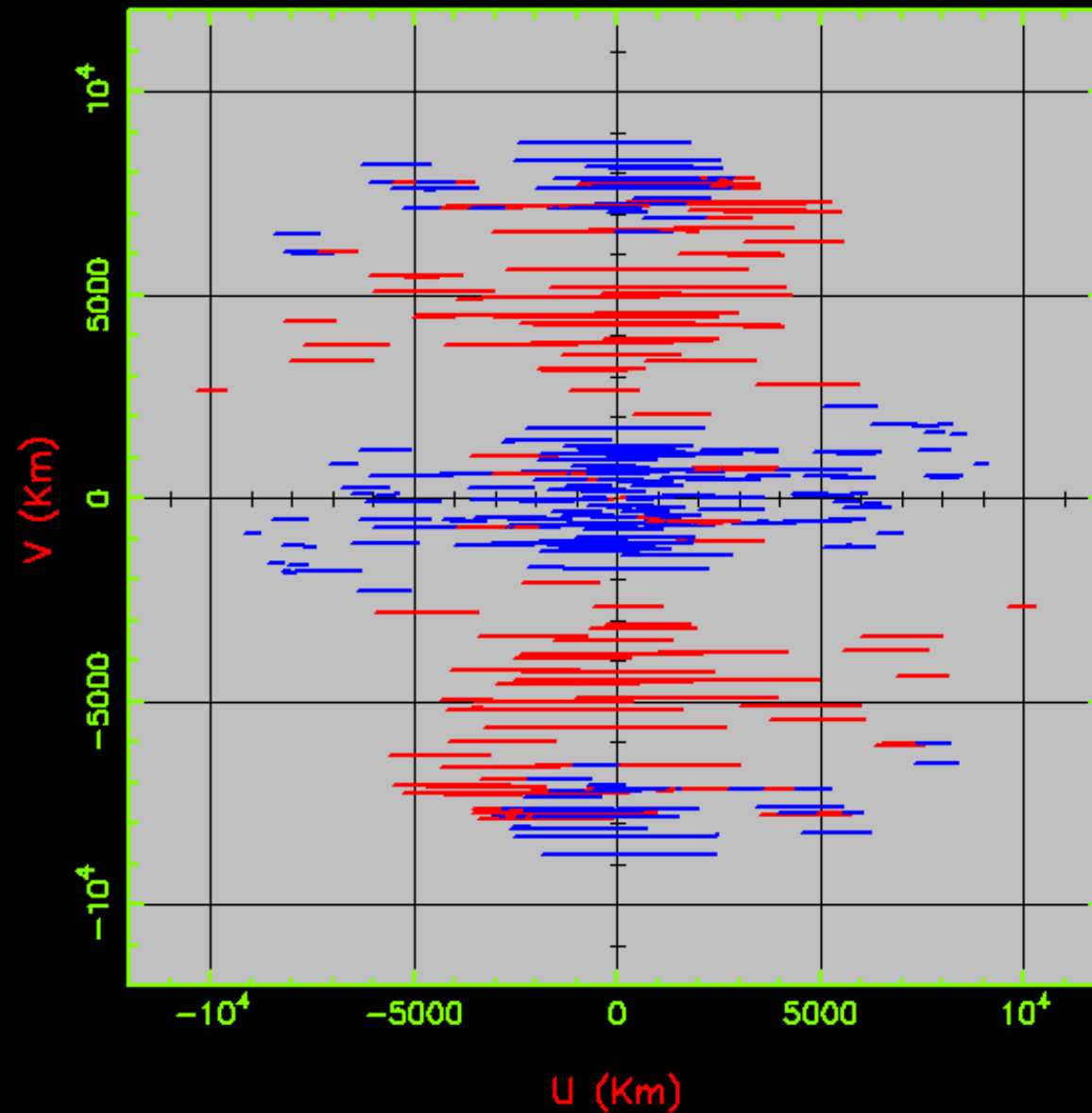
Aperture Synthesis

- One short integration with a single baseline at one wavelength gives one point in the uv plane
- The Earth's rotation will complete a track in the uv plane
- N telescopes gives $N(N-1)$ baselines
- Wider bandwidth fills the gaps in the uv plane



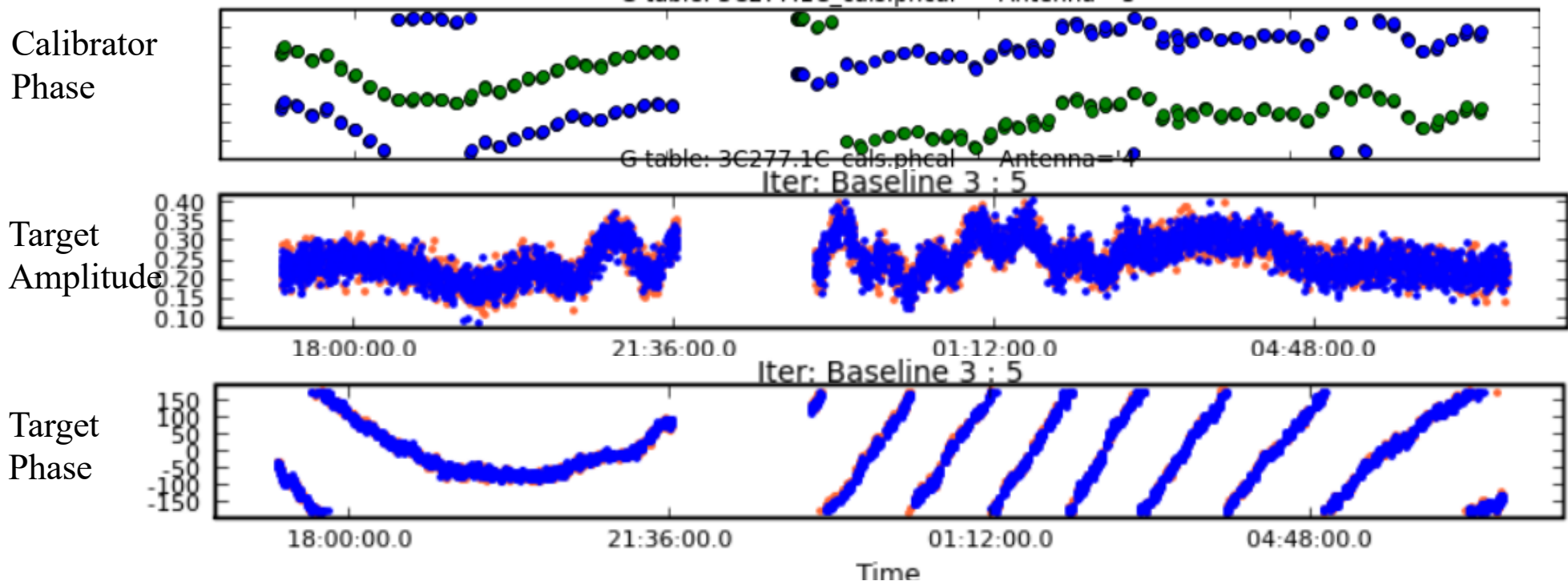
UV Coverage for Africa

HART
MEERKAT
GHANA
KENYA
MOZAMB
MAURIT
EB_VLBA
NOTO
TORUN
YEBES40M
MEDICINA
WSTRBORK
JODRELL1
GOONHILL
SHANGHAI
BADARY
ZELENCHK
SVETLOE
URUMQI
DECL=0

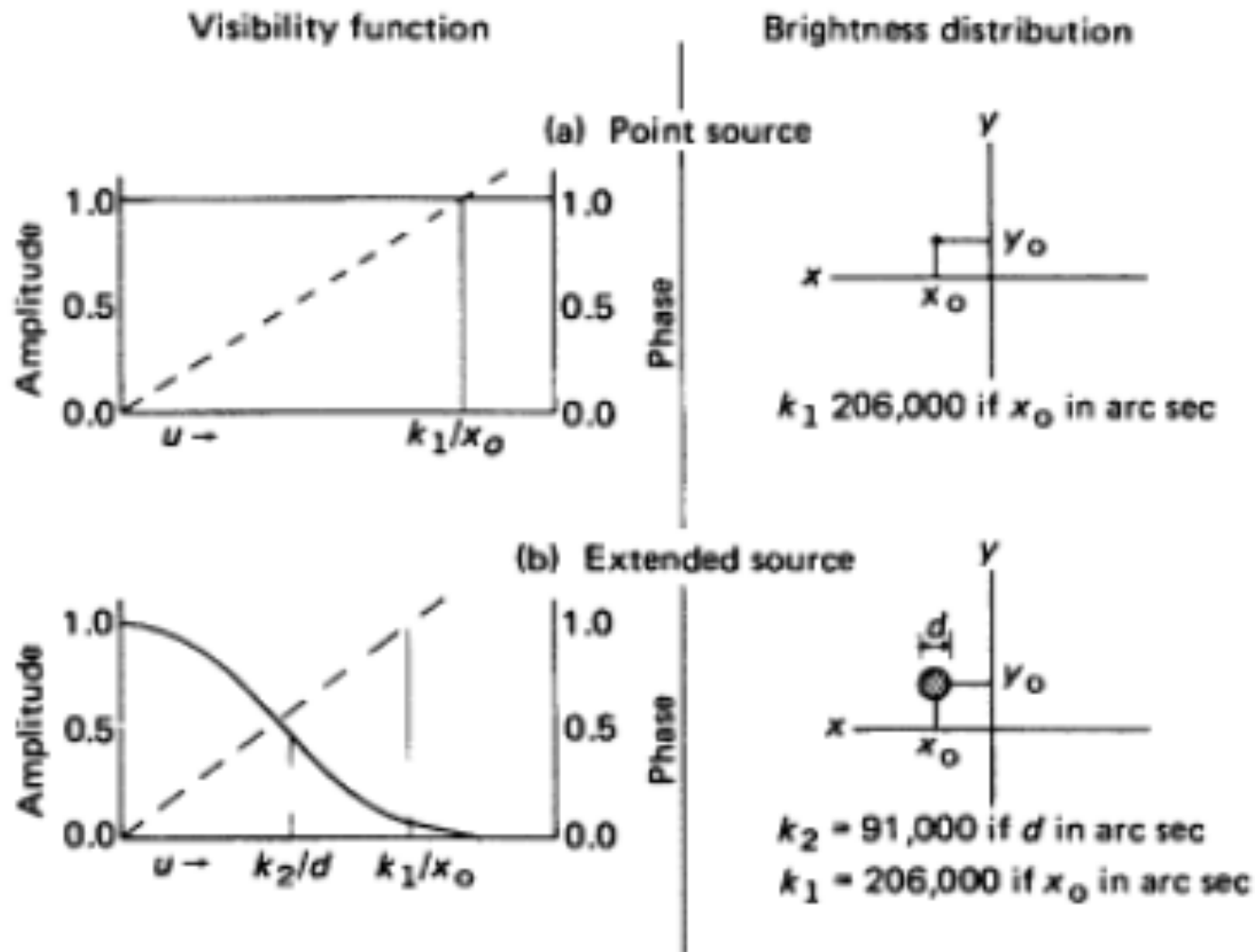


Calibration

- The effects of the atmosphere on the amplitude and phase are corrected by regular observations of a nearby, bright, point source e.g. a quasar



Amplitude vs Baseline plots



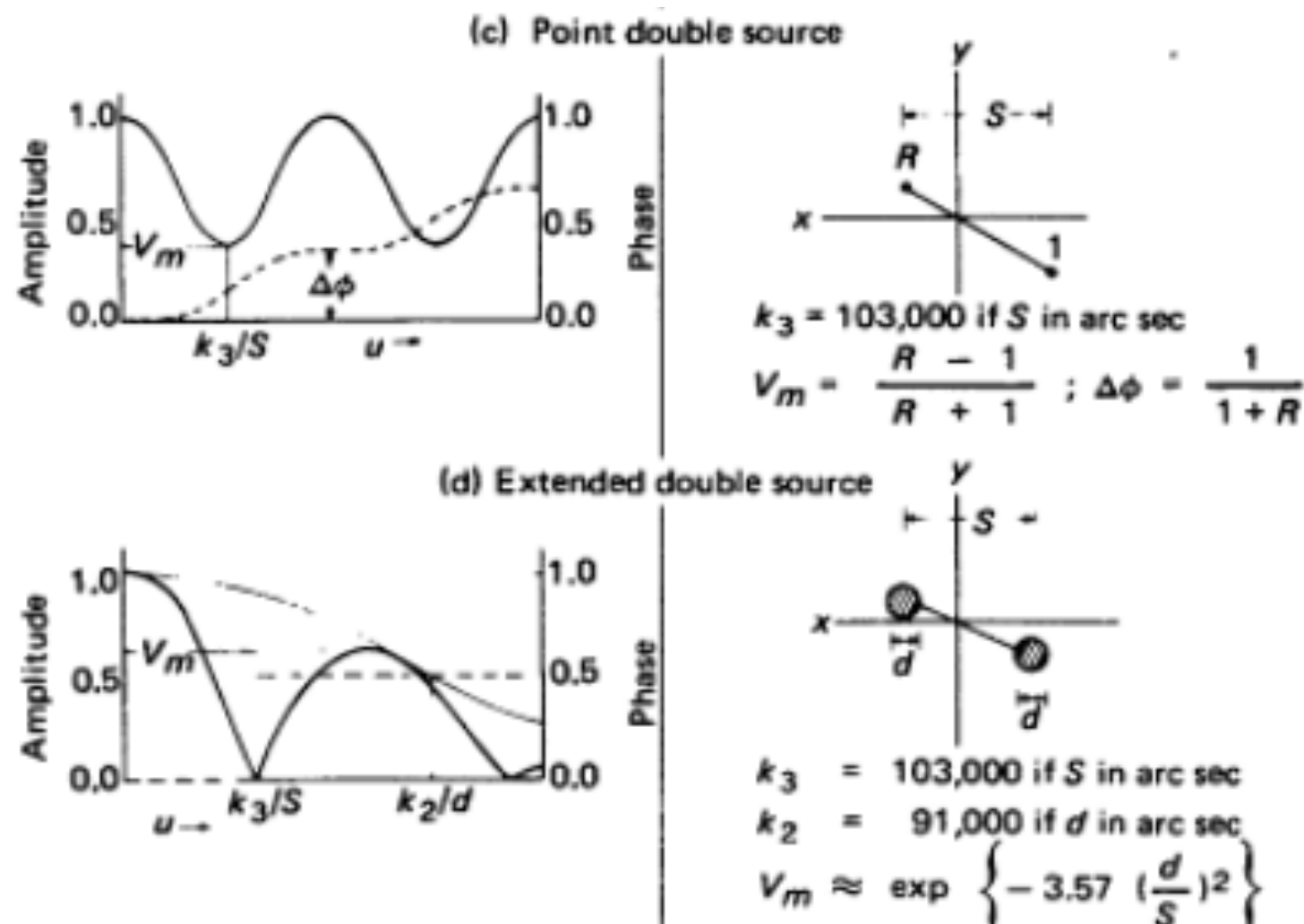


Figure 16-1. The visibility functions for various brightness distribution models (reproduced from Fomalont & Wright 1974; © Springer, Berlin).

Image Fidelity

- Maximum baseline determines the resolution or synthesised beam

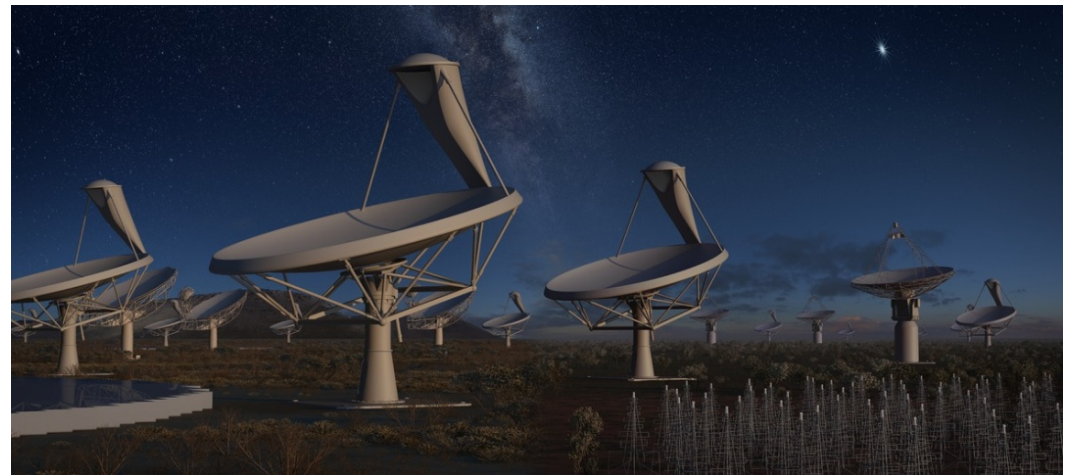
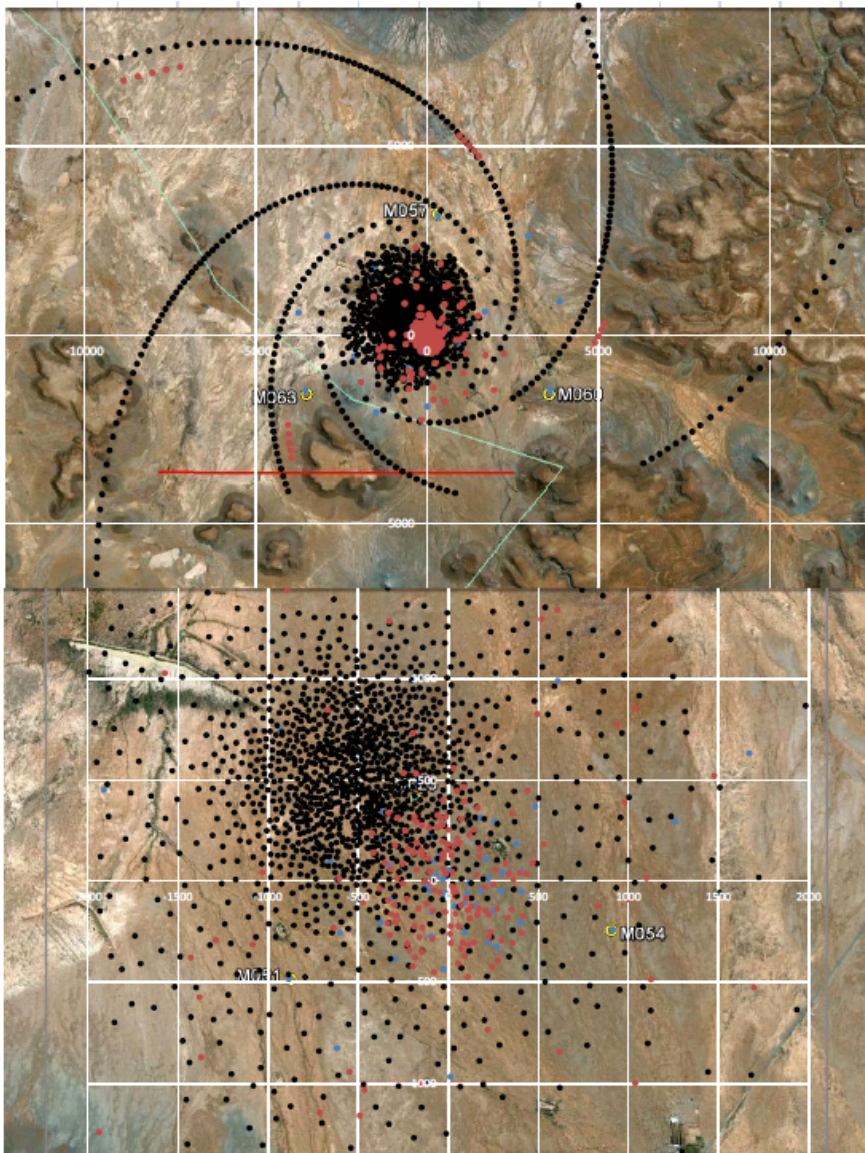
$$\theta_{beam} \approx \frac{\lambda}{b_{max}}$$

- Minimum baseline determines the largest angular scale that the interferometer can image

$$\theta_{LAS} \approx \frac{\lambda}{b_{min}}$$

- Emission at spatial frequencies larger than θ_{LAS} are not detected
- Often leads to *missing flux* issues
- Need to fill in missing short spacing information
- Image fidelity is determined by number of antenna in the array
- SKA with 3000 dishes and baselines from 30 m to 5000 km will solve many of these problems

SKA



Summary

- Interferometers observe the Fourier transform of the intensity distribution on the sky
- Only sensitive to a limited range of spatial frequencies
- SKA will be a massive leap forward

